

**Listing of All Claims Including Current Amendments**

1.-33. (Cancelled)

34. (Currently amended) Method of servicing outer components of a wind turbine with a work platform, said method comprising:

positioning the work platform at the wind turbine tower;

connecting the work platform to an upper part of the wind turbine with at least one cable;

raising the work platform with the cable and a cable winder to a position of use;

holding the work platform to a side of the wind turbine tower by directly gripping the tower with a holder comprised in the work platform; and

moving the work platform horizontally by extracting or retracting a horizontal forcer of the work platform;

wherein said horizontal forcer connects said holder with said work platform and comprises a number of horizontal forcing arms telescopically integrated into each other.

35. (Withdrawn) Method according to claim 34, wherein said holding is established with at least two sets of suction or vacuum cups.

36. (Withdrawn – Previously Presented) Method according to claim 34, wherein said holding is established with at least two sets of electromagnets.

37. (Previously Presented) Method according to claim 34, wherein said holding is established with a retainer surrounding said wind turbine tower.

38. (Withdrawn – Previously Presented) Method according to claim 34, wherein said holding is enhanced by positioning suction or vacuum cups or electromagnets on the ends of holding arms, said arms gripping around the exterior of the wind turbine tower.

39. (Cancelled).

40. (Currently Amended) Method according to claim 34, wherein the extracting or retracting is established telescopically by said horizontal forcing arms ~~a number of arm sections in said horizontal forcer.~~

41. (Previously Presented) Method according to claim 34, wherein cable guide angles the cable outwards in relation to the wind turbine tower from the starting point of the cable.

42. (Previously presented) Method according to claim 34, wherein said work platform is moved up or down by following and rolling with steering wheels of the platform on a surface of the wind turbine tower.

43. (Currently amended) Work platform for servicing outer components of a wind turbine, said platform comprising:

at least one cable connecting the work platform with an upper part of the wind turbine;

a cable winder winding said at least one cable; ~~and~~

a gripper for directly holding the work platform to the tower, said gripper comprising at least one holding arm including a base arm section, an inner arm section, and an outer arm section; and

a horizontal forcer connecting said gripper with said work platform, said forcer comprising a number of horizontal forcing arms telescopically integrated into each other;

wherein said inner arm section and said outer arm section are pivotally connected and controlled by a holding arm actuator in at least one direction; and

wherein said work platform is movable horizontally by extracting or retracting said horizontal forcer.

44. (Previously presented) Work platform according to claim 43, wherein said at least one cable comprises a set of outer cables, said set including a main cable and one or more additional cables.

45. (Previously Presented) Work platform according to claim 44, wherein said at least one cable further comprises an inner cable or cables.

46. (Previously Presented) Work platform according to claim 45, wherein said inner and outer cables are fixed to an underside of a wind turbine nacelle at an inner and outer anchorage point in a direction from the tower or to anchorage points inside the nacelle.

47. (Withdrawn – Previously Presented) Work platform according to claim 43, wherein said gripper comprises at least two sets of suction or vacuum cups.

48. (Withdrawn – Previously Presented) Work platform according to claim 43, wherein said gripper comprises at least two sets of electromagnets.

49. (Previously Presented) Work platform according to claim 43, wherein said gripper comprises a retainer surrounding the wind turbine tower.

50. (Withdrawn – Previously Presented) Work platform according to claim 47, wherein said gripper comprises at least two sets of suction or vacuum cups or electromagnets where such are flexibly mounted to an end of said holding arm.

51-52. (Cancelled).

53. (Previously Presented) Work platform according to claim 43, wherein gripper comprises one or more steering wheels.

54. (Previously presented) Work platform according to claim 43, wherein guard rails and a foundation define a work area of said platform.

55. (Previously Presented) Work platform according to claim 54, wherein said gripper and the foundation are connected through a horizontal forcer.

56. (Cancelled).

57. (Cancelled).

58. (Previously presented) Work platform according to claim 43, wherein a side or sides of said platform includes one or more indentations for receiving and docking one or more wind turbine blades.

59. (Previously Presented) Work platform according to claim 58, wherein said platform includes a retainer for retaining the wind turbine blade in one of said indentations.

60. (Previously Presented) Work platform according to claim 59, wherein said retainer includes one or more suction or vacuum cups positioned on one or more rods as a base part for the retainer.

61. (Previously Presented) Work platform according to claim 43, wherein said at least one cable is controlled by a cable guide.

62. (Previously Presented) Work platform according to claim 61, wherein a position of said cable guide controls an angling of the at least one cable.

63. (Previously Presented) Work platform according to claim 61, wherein said cable guide angles the cable outwards in relation to the wind turbine tower from an anchorage point of the cable.

64. (Previously Presented) Work platform according to claim 43, wherein said platform includes a control mechanism for controlling said holding arm actuator, a horizontal forcer, one or more suction or vacuum pumps and/or a cable winder.

65. (Previously Presented) Work platform according to claim 64, wherein said control mechanism is connected wired or wirelessly to and controlled by at least one remote control.

66. (Previously Presented) Work platform according to claim 64, wherein said control mechanism, said arm actuator, said horizontal forcer, said one or more suction or vacuum pumps and/or said cable winder are controlled with more than one remote control, said controls working in a master and slave configuration.